

# The Circumpolar Stratospheric Telescope – FUJIN – for Observations of Planets

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# Purpose

## Mercury

Na Atmosphere  
And Tail

## Jupiter

Aurora  
Satellites  
Io Torus  
Magnetosphere  
Cloud Physics  
Circulation  
Lightning

## Mars

Dust Storm  
Chemistry

## Venus (Dayside)

Circulation  
Temperature  
Chemistry

## Venus (Nightside)

Lightning  
Airglow

## Saturn

Aurora  
Titan



# Purpose

In order to understand time-dependent phenomena in the planetary atmospheres and plasmas,



- Long-term observation
  - 1 week ~ several months
  - Continuous for 24 hours
- High spatial resolution
- Monochromatic and multi-color
- Multi-purpose telescope

# Advantages of planetary observations by a circumpolar stratospheric telescope

- Stable atmospheric condition
  - Good seeing
  - Fine weather
- Small absorption and scattering
  - UV ( $O_3$ )
  - IR ( $H_2O$ ,  $CO_2$ , etc.)
  - Daytime observation
- Long-term observation from the polar stratosphere
- Multi-purpose
- Recoverable
  - Reusable
  - Improvement and upgrade
  - Low cost



# History of FUJIN Project

2002 Start of project

2009 1st experiment, failed due to failure in the onboard CPU

2010 Improvement

2011 Experiment cancelled due to delay of development

2012 Cancelled due to bad wind condition

2013 Cancelled due to malfunction in the bus system

Disadvantage of a balloon experiment: we cannot freely decide place and time of the experiment.

# Gondola Ready for Launch in 2013



- Size and weight:
  - 1.0 (W) x 1.0 (D) x 3.6 (H) m
  - 790kg (300 kg ballast incl.)
- Telescope:
  - Schmidt-Cassegrain type
  - $\phi$  300 mm,  $f=6000$  mm
  - Az-El mount
- Power Supply:
  - Li-ion battery (25.9 V 50 Ah)
  - Solar Cell Panel (240 Wmax)
- Telemetry:
  - Serial comm. 2400 bps (data down link and command uplink)
  - Double-tone command
  - NTSC analog composite video downlink

Long hoods, second star sensor, functional heaters have been added.

# Attitude Control and Pointing System

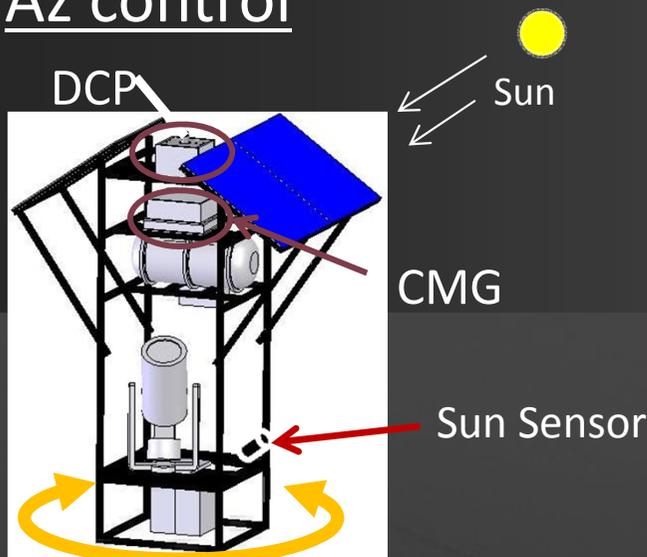
- Requirement:

Pointing error  
1/30 sec (video frame)

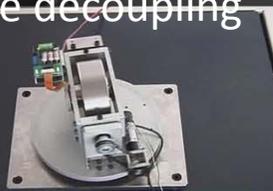
≈

Diffraction limit ( $\phi=300\text{mm}$ )  
= 0.34 arcsec ( $\lambda=400\text{nm}$ )  
0.75 arcsec ( $\lambda=700\text{nm}$ )

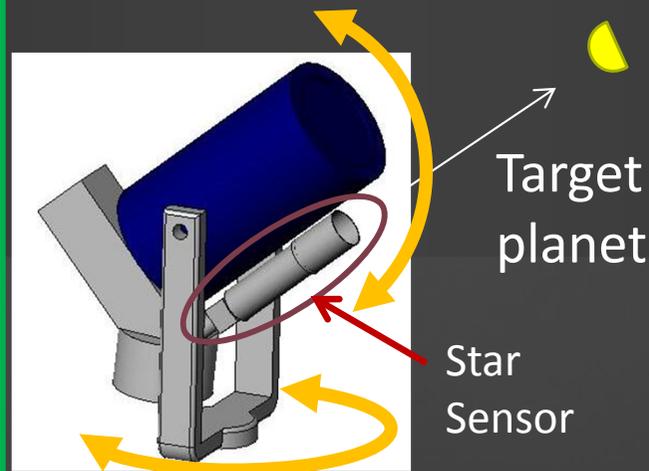
## Az control



Sun-oriented attitude  
Actuators: Control moment gyro (CMG)+Active decoupling motor (DCP)  
Accuracy: 0.5°

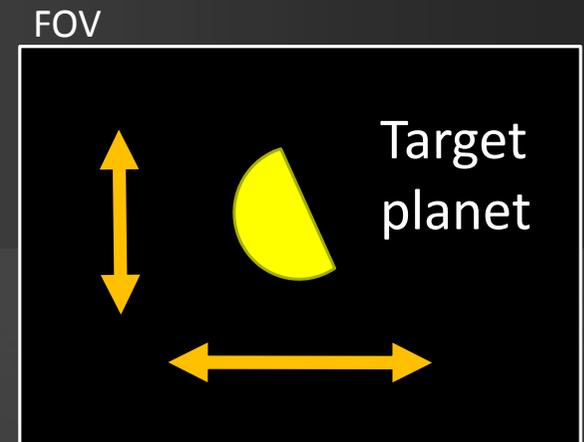


## Coarse guiding



Target-oriented  
Mount: Az-El gimbals  
Accuracy: 1'

## Fine guiding



Error correction  
Actuator: Tip-tilt mirror  
Accuracy: 0.1"



# Optical System

Observation CCD cameras  
CCD size : 1/2 inch  
FOV : 144 x 108 arcsec  
Resolution : 0.2 arcsec/pixel

IR camera  
 $\lambda = 750 \sim 1200 \text{ nm}$   
Diffraction limit : 0.7arcsec@900nm

Dichroic filters

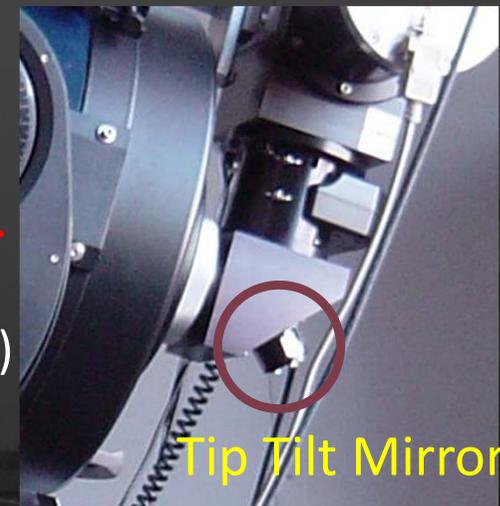
UV camera  
 $\lambda = 350 \sim 450 \text{ nm}$   
Diffraction limit :  
0.34arcsec@400nm

Multi-Anodes Photomultiplier Tube  
 $\lambda = 450 \sim 750 \text{ nm}$

2x Barlow Lens

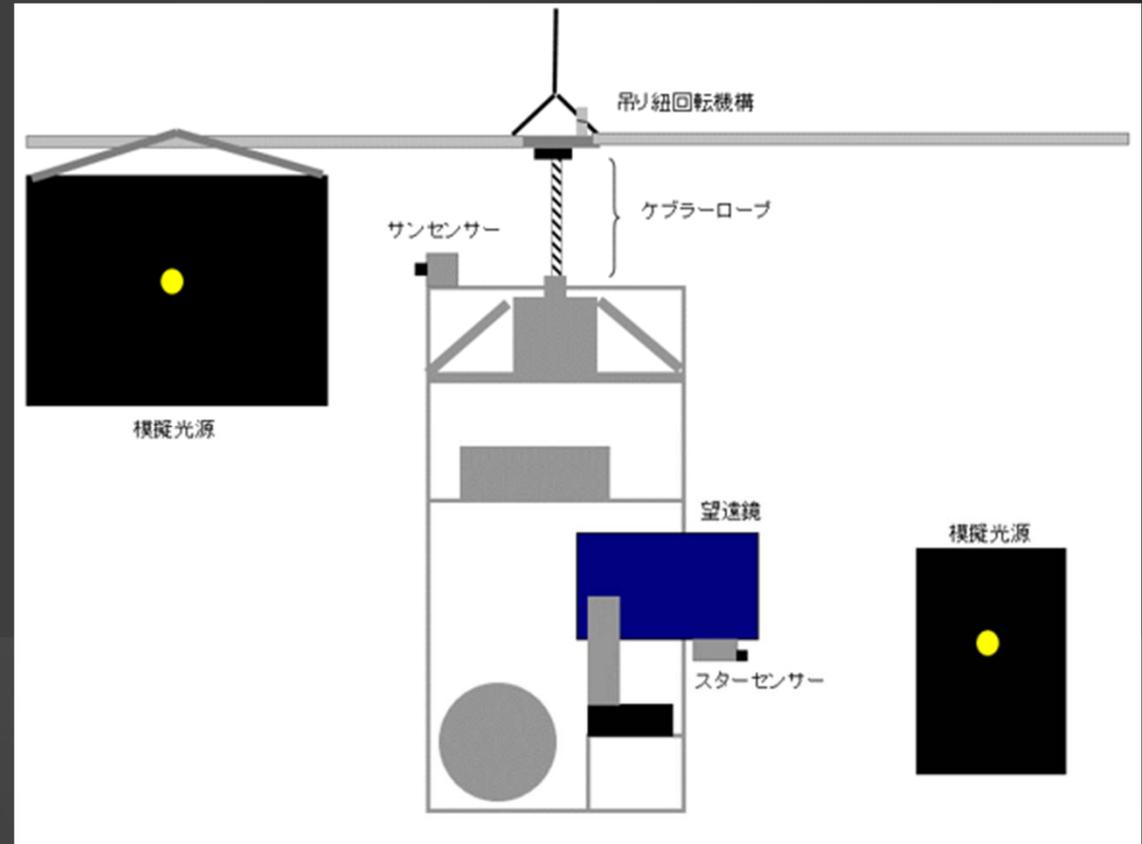
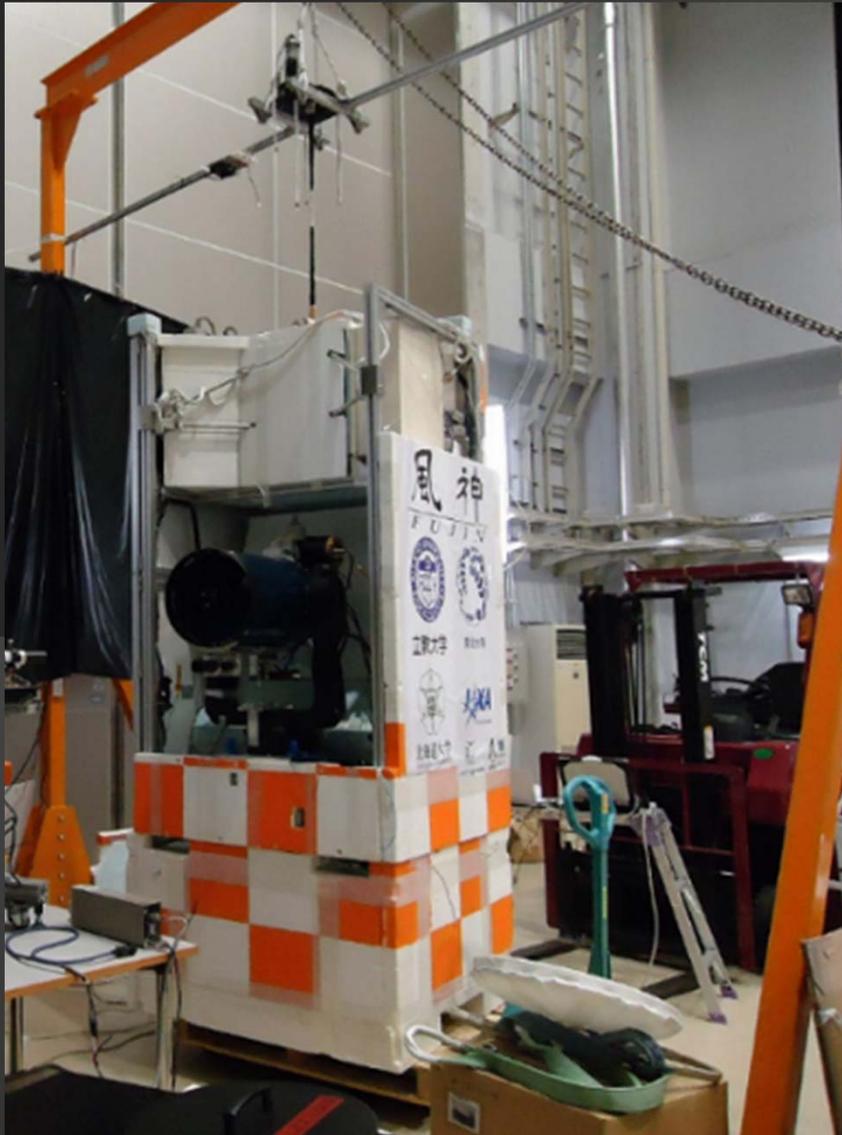
Tip-Tilt mirror  
(Piezo Actuated)

Schmidt Cassegrain Telescope  
 $\phi 300 \text{ mm}$ ,  $f=3048 \text{ mm}$



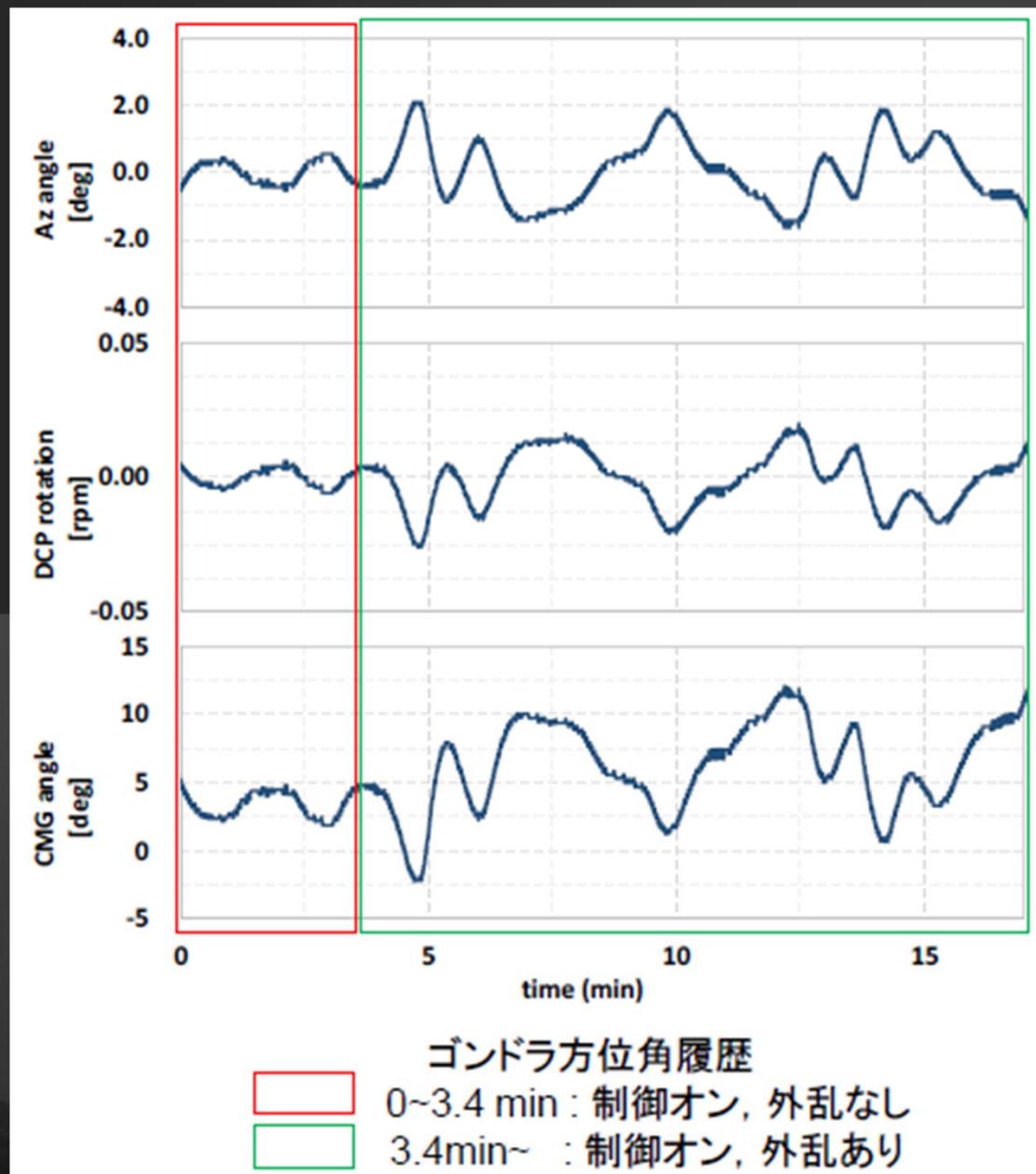
Tip Tilt Mirror

# Performance test of the attitude control and coarse guiding system — experimental setup



The gondola was hanged by a rope, and rotated by a rotator as a perturbation generator which simulates the flight condition.

# Performance test of the attitude control and coarse guiding system — result

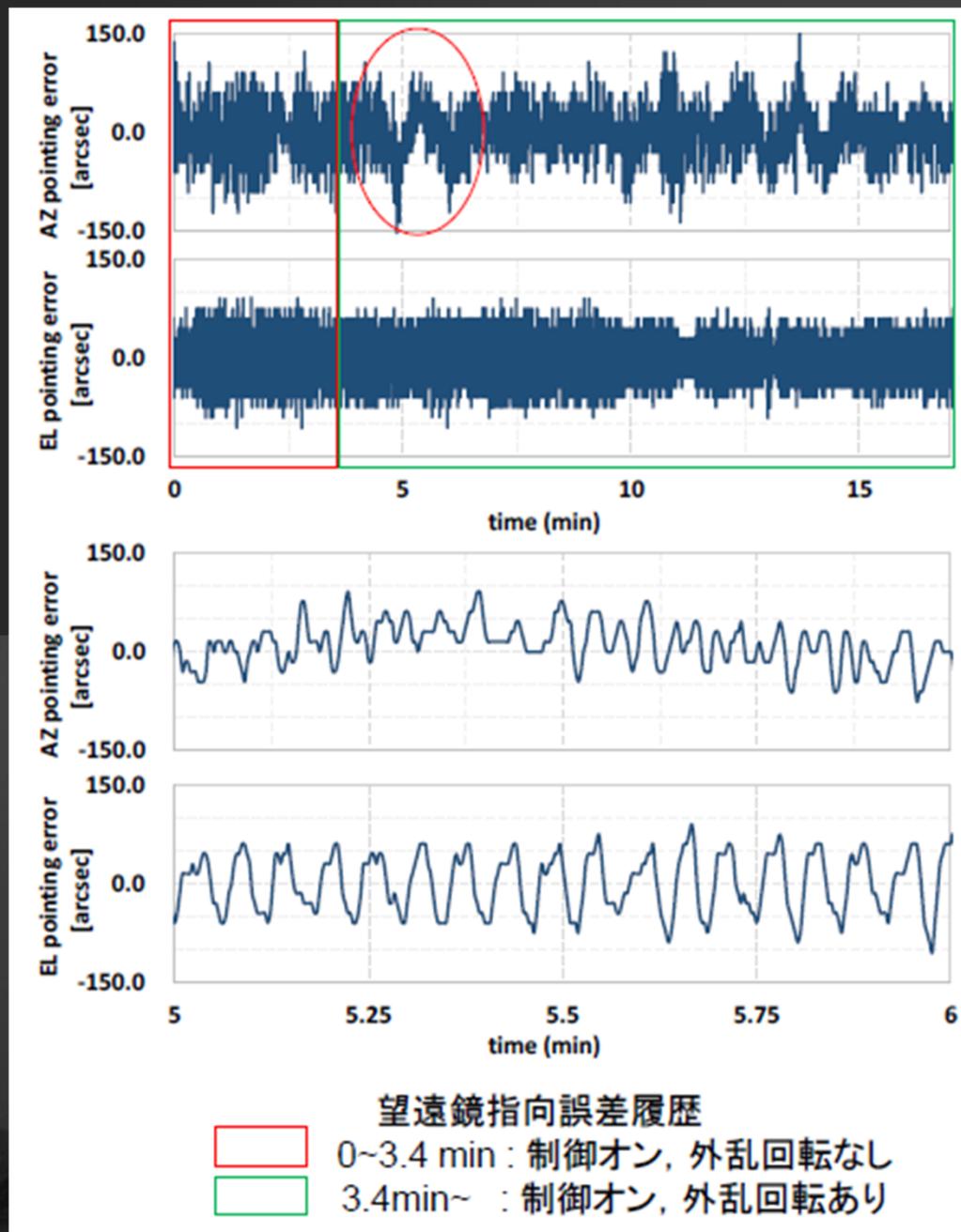


Perturbation:  $\pm 1/78$  rpm p-p, period 300 sec, added 3.4 min after the start of control.

The Az angle variation was  $1.5 \sim 2.0^\circ$  with a period of 300 sec

The star sensor kept locking on the artificial star, though the attitude control error exceeded the target value of  $0.5^\circ$ .

# Performance test of the attitude control and coarse guiding system — result



Pointing error:

Az: 36" rms

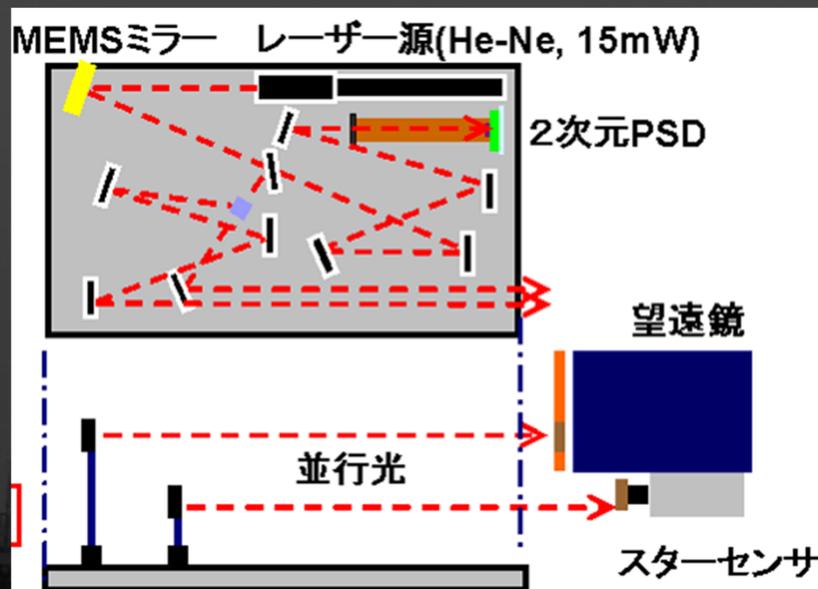
El: 42" rms

The motion of telescope generated an oscillation in the elevation axis with a period of 3~4 sec. This oscillation was generated by reaction of the gondola to the telescope motion, and should be improved in FUJIN-2 by introducing three-axis CMGs.

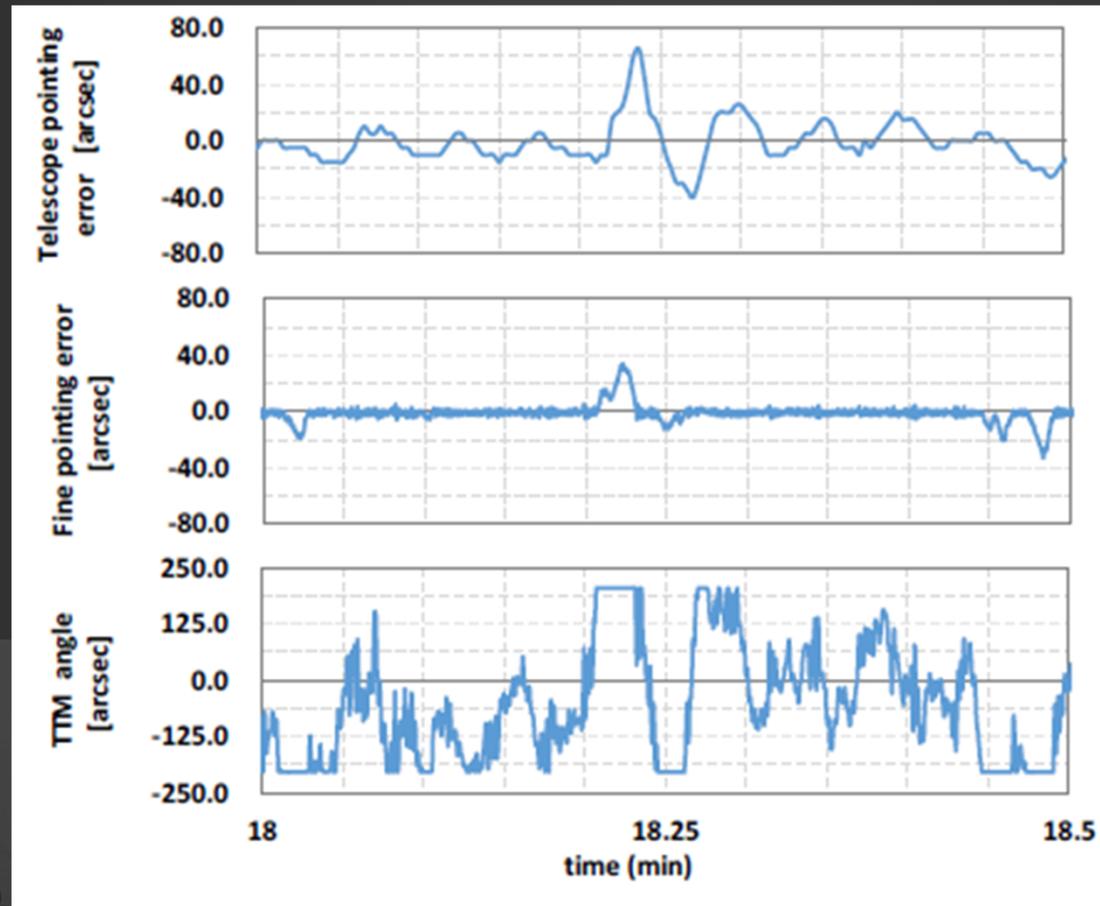
# Overall attitude control and guiding performance test using a laser light source



The gondola was hanged by a rope, which was rotated by a rotator as a perturbation generator. A laser was used as an artificial star light source of which the beam direction can be stirred by a vibrating mirror. Two parallel beams were introduced into the apertures of the telescope and star sensor.



# Overall attitude control and guiding performance test using a laser light source

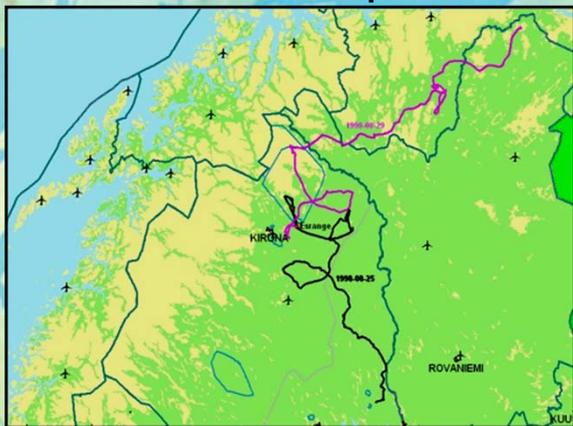


For the Az control the fine guiding was effective for 64% of the 2 min period from 17.09 min, and the guiding error was 1.7" rms. This is because the laser image was much larger than an image of a planetary disc, and the sensitivity of position detection became lower. The guiding error will be improved when the telescope looks at an actual planet.

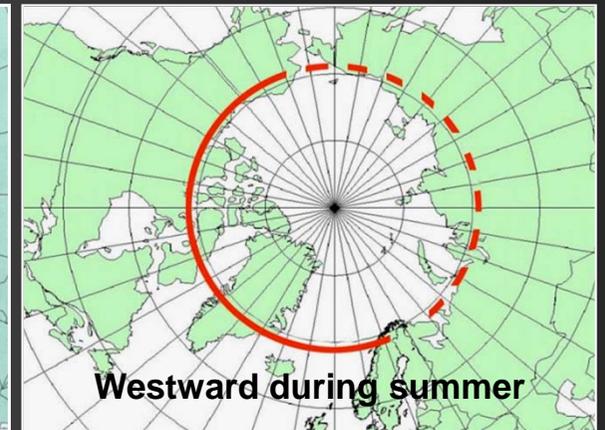
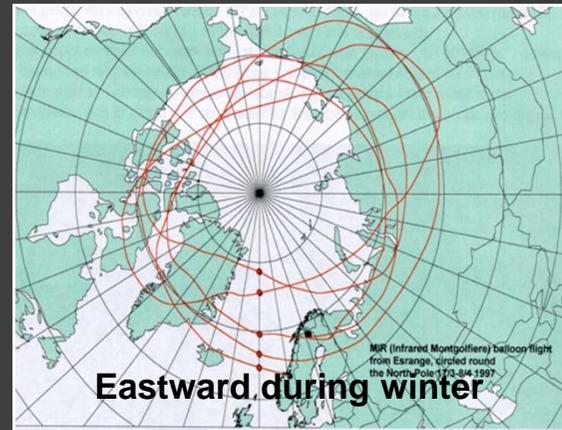
# FUJIN-2 Experiment Plan



Turn-around period



## Balloon trajectories



### Flight directions & duration:

**Turn-around:** Sweden (Finland/Norway)  
April/May & Aug/Sept. 1 – 4 days at float

**Winter:** Northern Finland, Kola Peninsula, ~ 10 h  
Siberia up to 25 h  
Circumpolar flights >14 Days

**Summer:** North America, 5 – 7 Days  
Circumpolar flights >14 Days

**Polarized Gamma-ray Observer (PoGOLite) has succeeded in a circumpolar flight in the summer in 2013.**

# FUJIN-2 Experiment Plan

April 30, 2015 12:00:00 LT



Purpose: Observations of Venus atmosphere

Launch: ESRANGE (Kiruna, Sweden)

Window: April/May, 2015

Flight duration: 24~48 hours

# FUJIN-2 Experiment Plan



The new telescope in a test observation. It will be installed in the gondola upside down.

## A new telescope

Type: Cassegrain + barlow lens

Focus: Nasmyth type

Aperture: 400 mm

F: 30~40 (continuously variable)

Filters: 10 bandpass filters

# Improvements after the experiment in 2009

Sub-system	Improvement
Controller	The onboard CPU has been replaced by an FPGA.
Electrical I/F	A slip ring has been inserted between the gondola and the balloon.
Power Supply	Main switch, waterproofing, Li-ion battery
Attitude control	Waterproofing of the CMG case
Data storage	SD memory cards
Structure	Reduced weight and height

