惑星探査機着陸機構 — 発展型 GMEID の提案 Planetary Exploration Spacecraft Landing Gear System - Proposal of Advanced GMEID 原進(名大) 大槻真嗣 翼(名大) (JAXA)〇渡辺 Tsubasa WATANABE*, Susumu HARA* and Masatsugu OTSUKI** *Nagoya University, **ISAS/JAXA

This paper discusses a planetary exploration spacecraft landing gear system on the basis of momentum exchange principles. The authors have already proposed the generalized momentum exchange impact damper (GMEID) that absorbs the controlled object's momentum with the damper masses. This presentation shows an advanced version of the GMEID (G-Advanced). G-Advanced reduces the number of damper masses and maintains similar rebound reduction performance in comparison with GMEID. The characteristics of G-Advanced are investigated by simulations.

BACKGROUND OF THE STUDY

MEID MECHANISM

Landing on all kinds of regions

may be happened.

Landing gear must prevent shock response

• Honeycomb crush[1] Can be used only once.

Low reliability High cost

• Sky crane[2] High cost

Landing gear with high reliability is needed.





Sky crane (NASA)

(Momentum Exchange Impact Damper : MEID)[3]

Transfer the controlled object's momentum to the damper mass



* P or H is filled in



PROBLEMS OF G-MEID

INTRODUCTION OF IMPROVED G-MEID

G-MEID has two remaining problems.



Load mass must be reduced.

- L-damper mass drops
- It may disrupt and pollute
- It may rebound and touch with the spacecraft.





Model with GA-HMEID

Tense the U-spring in advance and open it just before landing.



L-damper mass is not need.

 \rightarrow More equipment can be loaded.

More effective rebound reduction can be achieved.

Improvement of G-MEID is needed.

G-MEID-A SIMULATION

CONCLUSION

MEIDs are applied to the spacecraft's landing problems.



The problems of G-MEID are listed.

G-MEID-A mechanism is introduced.

Some simulation results show the effectiveness of G-MEID-A.

U-damper mass	m_{u}	0.69 kg
U-spring mass	<i>m</i> _{usp}	0.35 kg
L-damper mass	m_l	0.24 kg
L-spring mass	m_{lsp}	0.45 kg
Body mass	m_b	3.91 kg
Actuator maximum force		119 N
U-spring constant	k_u	20,000 N/m
L-spring constant	k_l	10,000 N/m
U-spring constant (G-MEID-A)	l_l	7,000 N/m
Initial compression amount of L-spring	а	0.020 m
Initial tension amount of U-spring	a	0.040 m
Initial height		0.50 m

REFERENCES

[1] Rogers, W. F., Apollo Experience Report Lunar Module Landing Gear Subsystem, NASA TN D-6850, NASA, (1972), pp.6-21.

[2] NASA, "Strange but True: Curiosity's Sky Crane". NASA SCIENCE - Home (online), available from http://science.nasa.gov/science-news/science-at-nasa/2012/30jul_skycrane/, (accessed 2012-11-29).

[3] Son, L., Hara, S., Yamada, K. and Matsuhisa, H., Experiment of Shock Vibration Control Using Active Momentum Exchange Impact Damper, Journal of Vibration and Control, Vol.16, No.1 (2010), pp.49-64.

[4] Hara, S., Ito, R., Otsuki, M., Yamada, Y., Kubota, T., Hashimoto, T., Matsuhisa, H. and Yamada, K., Momentum-Exchange-Impact-Damper-Based Shock Response Control for Planetary Exploration Spacecraft, Journal of Guidance, Control, and Dynamics, Vol.34, No.6, (2011), pp.1828-1838.

[5] Kushida, Y., Hara, S., Otsuki, M., Yamada, Y., Hashimoto, T. and Kubota, T., "Robust Landing Gear System Based on a Hybrid Momentum Exchange Impact Damper", to appear in Journal of Guidance, Control, and Dynamics.